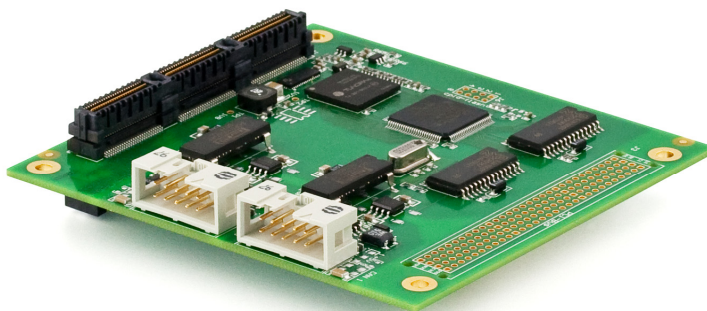


# PCAN-PCI/104-Express

PCI/104-Express to CAN Interface

User Manual v2.1.0



## Products taken into account

Product Name	Model	Part Number
PCAN-PCI/104-Express Single Channel	One CAN channel	IPEH-003054
PCAN-PCI/104-Express Dual Channel	Two CAN channels	IPEH-003055
PCAN-PCI/104-Express Single Channel opto- decoupled	One CAN channel, galvanic isolation for CAN connection	IPEH-003056
PCAN-PCI/104-Express Dual Channel opto- decoupled	Two CAN channels, galvanic isolation for CAN connections	IPEH-003057

The cover picture shows the product PCAN-PCI/104-Express Dual Channel opto-decoupled. Other product models have an identical form factor but vary in equipment.

On request you can get the product versions with stack-through connectors for the PCI bus

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Document version 2.1.0 (2011-11-03)

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# 1 Introduction

The PCAN-PCI/104-Express card allows the connection of one or two CAN networks to a PCI/104-Express-System. Device drivers and programming interfaces exist for different operating systems, so programs can easily access a connected CAN bus.



**Tip:** At the end of this manual (Appendix C) you can find a [Quick Reference](#) with brief information about the installation and operation of the PCAN-PCI/104-Express card.

## 1.1 Properties at a Glance

- └ PCI/104-Express card, 1 Lane (x1)
- └ Form factor PC/104
- └ Up to 3 cards can be used in one system
- └ 1 or 2 High-speed CAN channels (ISO 11898-2)
- └ Bit rates up to 1 Mbit/s
- └ Compliant with CAN specifications 2.0A (11-bit ID) and 2.0B (29-bit ID)
- └ CAN bus connection via D-Sub, 9-pin (in accordance with CiA® 102)
- └ NXP SJA1000 CAN controller
- └ NXP PCA82C251 CAN transceiver
- └ Galvanic isolation on the CAN connection up to 500 V (only opto-decoupled models), separate for each connector
- └ PCI-104 stack-through connector

- └ 5-Volts supply to the CAN connector can be connected through solder jumper, e.g. for external bus converter
- └ Extended operating temperature range from -40 to 85 °C (-40 to 185 °F)



**Note:** This manual describes the use of the PCAN-PCI/104-Express card with **Windows**. You can find device drivers for **Linux** and the corresponding application information on the provided CD in the directory branch `Develop` and on our website under [www.peak-system.com/linux](http://www.peak-system.com/linux).

## 1.2 System Requirements

- └ PC/104 stack with PCIe/104 connectivity to the host
- └ Operating system Windows 7/Vista/XP (32/64-bit) or Linux (32/64-bit)

## 1.3 scope of supply

- └ PCAN-PCI/104-Express card
- └ Slot bracket with D-Sub connectors for the CAN bus
- └ Device drivers for Windows 7/Vista/XP (32/64-bit) and Linux (32/64-bit)
- └ PCAN-View CAN monitor for Windows
- └ PCAN-Basic programming interface consisting of an interface DLL, examples, and header files for all common programming languages
- └ Manual in PDF format

## 2 Installing the Software and the Card

This chapter covers the software setup for the PCAN-PCI/104-Express card under Windows and the installation of the card in the PC/104 stack (short: stack).



**Note:** Under Windows the PCAN-PCI/104-Express card is run as a PCI card.

Setup the driver before inserting the card into the stack.



Do the following to install the driver:

1. Windows XP only: Make sure that you are logged in as user with administrator privileges (not needed for normal use of the card later on).
2. Insert the supplied CD into the appropriate drive of the computer. Usually a navigation program appears a few moments later. If not, start the file `Intro.exe` from the root directory of the CD.
3. On the page **English > Drivers** activate the entry **PCAN-PCI**.
4. Click on **Install now**. The setup program for the driver is executed.
5. Follow the instructions of the program.



**Tip:** If you don't want to install the CAN monitor PCAN-View for Windows onto the hard disk together with the driver, you have the option to start the program later directly from CD without prior installation.

▶ Do the following to insert the card into the stack:



**Note:** PCI/104-Express cards must always be positioned next to the host.

1. Shutdown the system and disconnect it from the power supply.
2. Insert the card into the stack next to the host or to another PCI/104-Express card.  
  
A maximum of 3 PCI/104-Express cards per stack is possible, either all on top or all beneath the host.
3. Plug a cable from the slot bracket to a 10-pin socket for each CAN connection.
4. Reconnect the power supply of the system.

▶ Do the following to complete the initialization:

1. Turn on the system and start Windows. Make sure that you are logged in as user with administrator privileges.

Windows notifies that new hardware has been detected.

2. Windows XP only: A Wizard dialog box appears. Follow its instructions. Deny the search for driver software at Windows Update and select the automatic software installation during the procedure.

All Windows operating systems: The drivers are found and installed by Windows.

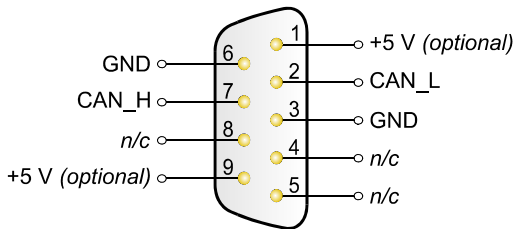
3. Afterwards you can work as user with restricted rights again.

After the driver has been successfully set up you can find the entry "PCAN-PCI" in the branch "CAN-Hardware" of the Windows Device Manager.

## 3 Connecting the CAN Bus

### 3.1 D-Sub connector

A High-speed CAN bus (ISO 11898-2) is connected to the 9-pin D-Sub connector. The pin assignment corresponds to the specification CiA® 102.



*n/c* = not connected

Figure 1: Pin assignment High-speed CAN



The pin assignment between the D-Sub port and the 10-pin connector on the PCAN-PCI/104-Express card is as follows:

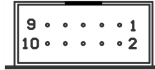


Figure 2: Numbering at the 10-pin connector

Pin	Assignment	Assignment D-Sub
1	+5 V (optional)	1
2	GND	6
3	CAN_L	2
4	CAN_H	7
5	GND	3
6	not connected	8
7	not connected	4
8	+5 V (optional)	9
9	not connected	5
10	not connected	



**Tip:** You can connect a CAN bus with a different transmission standard via a bus converter. PEAK-System offers different bus converter modules (e.g. PCAN-TJA1054 for a Low-speed CAN bus according to ISO 11898-3).

## 3.2 Supplying External Devices via the CAN Connector

A 5-Volt supply can optionally be routed to pin 1 and/or pin 9 of a D-Sub connector by setting solder bridges on the PCAN-PCI/104-Express card (independently for each connector on the Dual Channel models). Thus devices with low power consumption (e.g. bus converters) can be directly supplied via the CAN connector.

When using this option the 5-Volt supply is connected to the power supply of the computer and is not fused separately. The opto-decoupled models of the card contain an interconnected DC/DC converter. Therefore the current output is limited to 50 mA.

➡ Proceed as follows to activate the 5-Volt supply:

Set the solder bridge(s) on the card according to the desired settings. During this procedure take especially care not to produce unwanted short circuits on the card.

Figure 3 shows the positions of the solder fields on the card. The table below contain the possible settings.



## 3.3 Cabling

### 3.3.1 Termination

A High-speed CAN bus (ISO 11898-2) must be terminated on both ends with 120 Ohms. Otherwise, there are interfering signal reflections and the transceivers of the connected CAN nodes (CAN interface, control device) will not work.

The PCAN-PCI/104-Express card does not have an internal termination. Use the adapter on a terminated CAN bus.

### 3.3.2 Example of a Connection

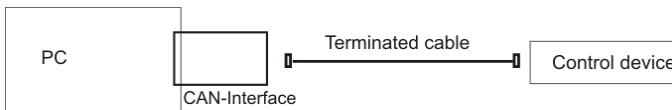


Figure 4: Simple CAN connection

In this example, the PCAN-PCI/104-Express card is connected with a control unit by a cable that is terminated at both ends.

### 3.3.3 Maximum Bus Length

High-speed CAN networks may have bit rates of up to 1 Mbit/s, where all CAN nodes must be able to process messages simultaneously. The maximum bus length depends primarily on the bit rate.

The following table shows the maximum possible CAN bus length at different bit rates:

Bit rate	Bus length
1 Mbit/s	40 m
500 kbit/s	110 m
250 kbit/s	240 m
125 kbit/s	500 m
50 kbit/s	1,3 km
20 kbit/s	3,3 km
10 kbit/s	6,6 km
5 kbit/s	13,0 km

The listed values have been calculated on the basis of an idealized system and can differ from reality.

## 4 Using the Software

This chapter covers the provided software PCAN-View and the programming interface PCAN-Basic.

### 4.1 CAN Monitor PCAN-View for windows

PCAN-View for Windows is a simple CAN monitor for viewing, transmitting, and logging CAN messages.

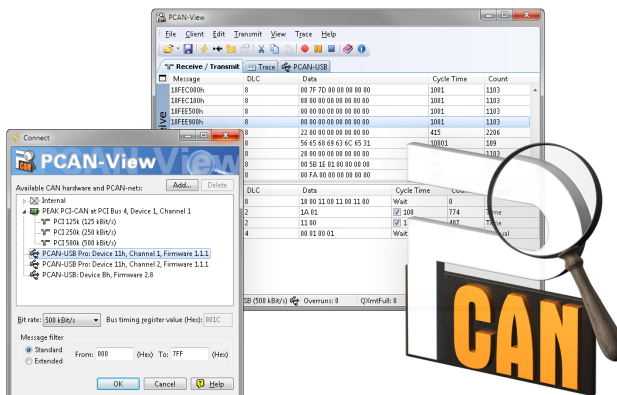


Figure 5: PCAN-View for Windows

► Do the following to start and initialize PCAN-View:

1. If PCAN-View is already installed on the hard disk, open the Windows Start menu, go to **Programs > PCAN-Hardware**, and select the entry **PCAN-View**.

If you haven't installed PCAN-View together with the device driver, you can start the program directly from the supplied CD. In the navigation program (Intro.exe) go to **English > Tools**, and under **PCAN-View for Windows** select the link **Start**.

The dialog box for selecting the CAN hardware and for setting the CAN parameters appears.

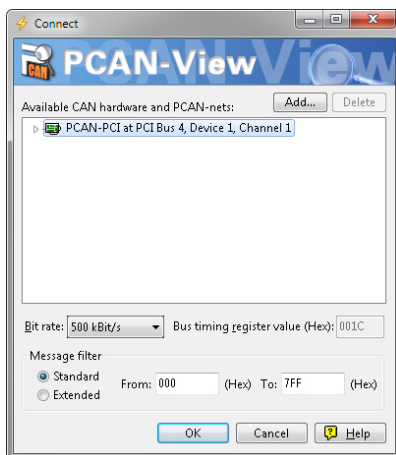
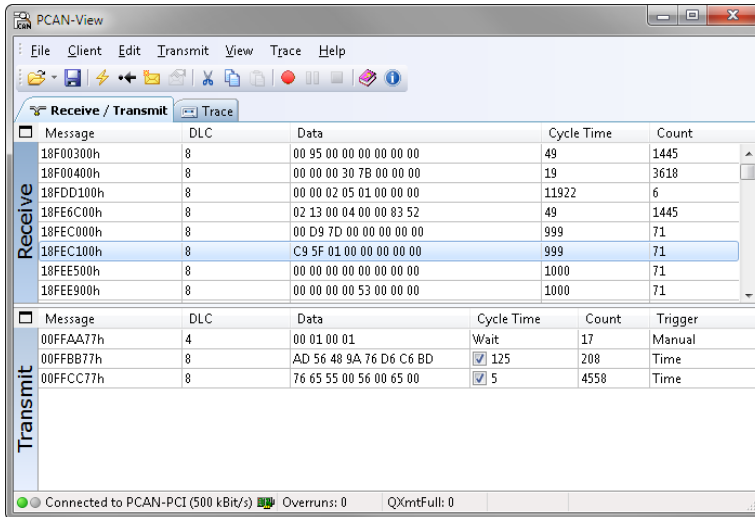


Figure 6: Selection of the CAN hardware and parameters

2. From the list **Available CAN hardware** select the CAN channel to be used.
3. Select the bit rate that is used by all nodes on the CAN bus from the list **Bit rate**.
4. Under **Filter settings** you can limit the range of CAN IDs to be received, either for standard frames (11-bit IDs) or for extended frames (29-bit IDs).
5. Finally confirm the settings in the dialog box with **OK**. The main window of PCAN-View appears (see Figure 7).

### 4.1.1 Receive/Transmit Tab



Message	DLC	Data	Cycle Time	Count
18F00300h	8	00 95 00 00 00 00 00 00	49	1445
18F00400h	8	00 00 00 30 7B 00 00 00	19	3618
18FDD100h	8	00 00 02 05 01 00 00 00	11922	6
18FE6C00h	8	02 13 00 04 00 00 83 52	49	1445
18FEC000h	8	00 D9 7D 00 00 00 00 00	999	71
18FEC100h	8	C9 5F 01 00 00 00 00 00	999	71
18FEE500h	8	00 00 00 00 00 00 00 00	1000	71
18FEE900h	8	00 00 00 00 53 00 00 00	1000	71


  

Message	DLC	Data	Cycle Time	Count	Trigger
00FFAA77h	4	00 01 00 01	Wait	17	Manual
00FFBB77h	8	AD 56 48 9A 76 D6 C6 BD	<input checked="" type="checkbox"/> 125	208	Time
00FFCC77h	8	76 65 55 00 56 00 65 00	<input checked="" type="checkbox"/> 5	4558	Time

Figure 7: Receive/Transmit tab

The Receive/Transmit tab is the main element of PCAN-View. It contains two lists, one for received messages and one for the transmit messages. Representation of CAN data is in hexadecimal format.

▶ Do the following to transmit a CAN message with PCAN-View:

1. Select the menu command **Transmit > New Message** (alternatively  or **Ins**).

The dialog box **New Transmit Message** is shown.



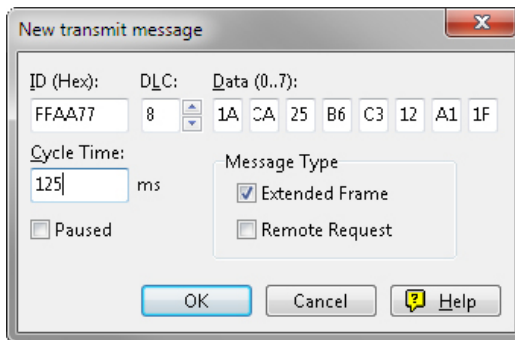


Figure 8: Dialog box New transmit message

2. Enter the ID and the data for the new CAN message.
3. The field **Cycle Time** indicates if the message shall be transmitted manually or periodically. If you want to transmit the message periodically, you must enter a value greater than 0. For a manual-only transmission enter 0.
4. Confirm the entries with **OK**.

The created transmit message appears on the **Receive/Transmit** tab.

5. You trigger selected transmit messages manually with the menu command **Transmit > Send** (alternatively **Space** bar). The manual transmission for CAN messages being transmitted periodically is carried out additionally.



**Tip:** Using the menu command **File > Save** the current transmit messages can be saved to a list and loaded for reuse later on.

## 4.1.2 Trace Tab

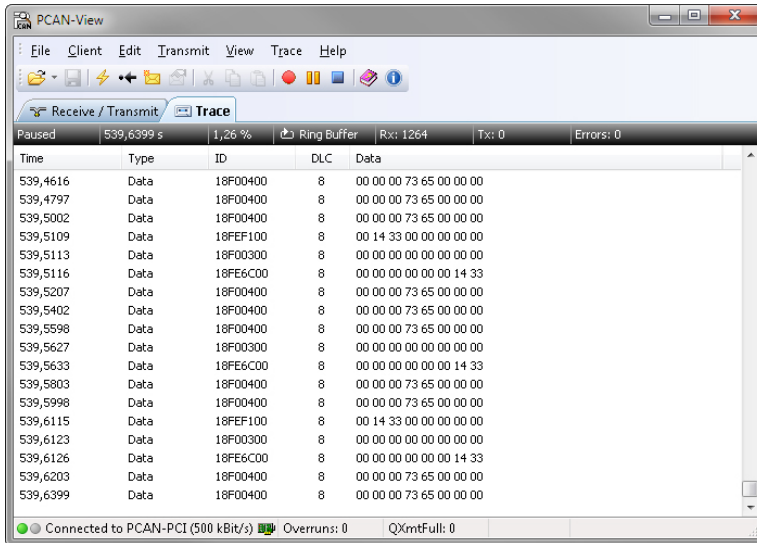


Figure 9: Trace tab

On the Trace tab the data tracer of PCAN-View is used for logging the communication on a CAN bus. During this process the CAN messages are cached in the working memory of the PC. Afterwards they can be saved to a file.

The tracer can be configured to run in linear or in ring buffer mode. In linear buffer mode the logging is stopped as soon as the buffer is filled completely. In ring buffer mode the oldest messages are overwritten by incoming ones.

### 4.1.3 Status Bar



Figure 10: Display of the status bar

The status bar shows information about the current CAN connection, about error counters (Overruns, QXmtFull), and shows error messages.

You can find further information about the use of PCAN-View in the help which you can invoke in the program via the menu **Help** or the **F1** key.

## 4.2 Linking Own Programs with PCAN-Basic

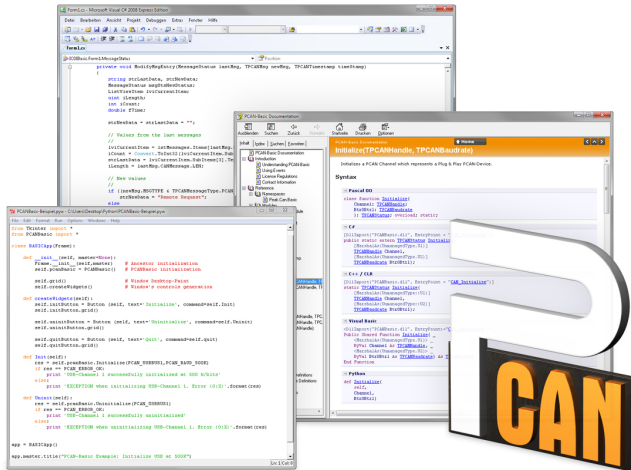


Figure 11: PCAN-Basic

On the provided CD you can find files of the programming interface PCAN-Basic in the directory branch `Develop`. This API provides basic functions for linking own programs to CAN interfaces by PEAK-System and can be used for the following operating systems:

- Windows 7/Vista/XP (32/64-bit)
- Windows CE 6.x (x86/ARMv4)

The API is designed for cross-platform use. Therefore software projects can easily be ported between platforms with low efforts. PEAK-System has created examples for the following programming languages: C++, C#, C++/CLR, Visual Basic, Delphi, Python, and Java.

### 4.2.1 Features of PCAN-Basic

- └ Multiple PEAK-System applications and a single one of your own can be used on a physical CAN channel at the same time
- └ A single DLL for all supported hardware types
- └ Use of up to 8 channels for each hardware unit (depending on the CAN interface used)
- └ Easy switching between the channels of a CAN interface
- └ Driver-internal buffer for 32768 messages per CAN channel
- └ Receive timestamp for CAN messages
- └ Real-time precision of the received messages down to 1  $\mu$ s
- └ Access to some hardware parameters, such as listen-only mode
- └ Notification through Windows events when a message is received
- └ Extended system for debugging operations
- └ Debugging information can be defined individually

An overview of the API functions is located in the header files. You can find detailed information about the PCAN-Basic API on the provided CD in the text and help files (file name extensions `.txt` and `.chm`).

## 4.2.2 Principle Description of the API

The PCAN-Basic API is the interface between the user application and device driver. In Windows operating systems this is a DLL (Dynamic Link Library).

The sequence of accessing the CAN interface is divided into three phases:

1. Initialization
2. Interaction
3. Completion

### Initialization

A CAN channel must be initialized before using it. This is done by the simple call of the function `CAN_Initialize`. Depending on the type of the CAN hardware, up to eight CAN channels can be opened at the same time. After a successful initialization the CAN channel is ready for communication with the CAN hardware and the CAN bus. No further configuration steps are required.

### Interaction

For receiving and transmitting CAN messages the functions `CAN_Read` and `CAN_Write` are available. Additional settings can be made, e.g. setting up message filters to confine to specific CAN IDs or setting the CAN controller to listen-only mode.

When receiving CAN messages, events are used for an automatic notification of an application (client). This offers the following advantages:

- The application no longer needs to check for received messages periodically (no polling).
- The response time at reception is reduced.

## Completion

To end the communication the function `CAN_Uninitialize` is called in order to release the reserved resources for the CAN channel, among others. In addition the CAN channel is marked as "Free" and is available to other applications.

### 4.2.3 Notes about the License

Device drivers, the interface DLL, and further files needed for linking are property of the PEAK-System Technik GmbH and may be used only in connection with a hardware component purchased from PEAK-System or one of its partners. If a CAN hardware component of third-party suppliers should be compatible to one of PEAK-System, then you are not allowed to use or to pass on the driver software of PEAK-System.

If a third-party supplier develops software based on the PCAN-Basic and problems occur during the use of this software, consult the software provider.

## 5 Technical specifications

### PCAN-PCI/104-Express

#### Connectors

PC/104 stack	PCIe/104, PCI Express x1 (1 Lane) Stack-through PCI/104-Bus, equipped with contact strip on request
CAN	D-Sub (m), 9 pins Pin assignment according to specification CiA® 102

#### CAN

Specification	ISO 11898-2 High-speed CAN (33 kbit/s - 1 Mbit/s) 2.0A (standard format) and 2.0B (extended format)
Controller	NXP (Philips) SJA1000
Transceiver	NXP (Philips) PCA82C251
Galvanic isolation	PCAN-PCI/104-Express: none PCAN-PCI/104-Express opto: up to 500 V separate for each CAN channel
Supplying external devices	PCAN-PCI/104-Express: D-Sub Pin 1; 5 V, max. 100 mA PCAN-PCI/104-Express opto: D-Sub Pin 1; 5 V, max. 50 mA Not assigned at delivery
Termination	none

#### Power supply

Current consumption (max.)	at 3.3-V pin at 5-V pin	
	Product model	
	Single Channel:	250 mA 50 mA
	Dual Channel:	250 mA 75 mA
	Single Channel opto:	250 mA 120 mA
	Dual Channel opto:	250 mA 150 mA

Continued on the next page



**Measures**

Size	90.1 x 95.9 mm (W x L) See also <a href="#">dimension drawing</a> in Appendix B on page 27
Weight	Product model Single Channel: 42 g Dual Channel: 47 g Single Channel opto: 44 g Dual Channel opto: 50 g

**Environment**

Operating temperature	-40 - +85 °C (-40 - +185 °F)
Temperature for storage and transport	-40 - +125 °C (-40 - +257 °F)
Relative humidity	15 - 90 %, not condensing
EMC	EN 55024:2003-10 EN 55022:2007-04 EC directive 2004/108/EG

# Appendix A CE Certificate

PCAN-PCI/104-Express IPEH-003054/55/56/57 - EC Declaration of Conformity  
PEAK-System Technik GmbH



## Notes on the CE Symbol

The following applies to the PCAN-PCI/104-Express products IPEH-003054/55/56/57

### EC Directive

This product fulfills the requirements of EC directive 2004/108/EG on "Electromagnetic Compatibility" and is designed for the following fields of application as per the CE marking:

### Electromagnetic Immunity

DIN EN 55024, Publication date: 2003-10  
Information technology equipment, immunity characteristics – Limits and methods of measurement (IEC/CISPR 24:1997, modified + A1:2001 + A2:2003);  
German version EN 55024:1998 + A1:2001 + A2:2003

### Electromagnetic Emission

DIN EN 55022, Publication date: 2008-05  
Information technology equipment – Radio disturbance characteristics – Limits and methods of measurement (IEC/CISPR 22:2005, modified + A1:2005);  
German version EN 55022:2006 + A1:2007

### Declarations of Conformity

In accordance with the above mentioned EU directives, the EC declarations of conformity and the associated documentation are held at the disposal of the competent authorities at the address below:

#### PEAK-System Technik GmbH

Mr. Wilhelm  
Otto-Roehm-Strasse 69  
64293 Darmstadt  
Germany

Phone: +49 (0)6151 8173-20  
Fax: +49 (0)6151 8173-29  
E-mail: [info@peak-system.com](mailto:info@peak-system.com)

A handwritten signature in black ink, appearing to read "V. Wilhelm".

Signed this 4<sup>th</sup> day of October 2011

## Appendix B Dimension Drawing

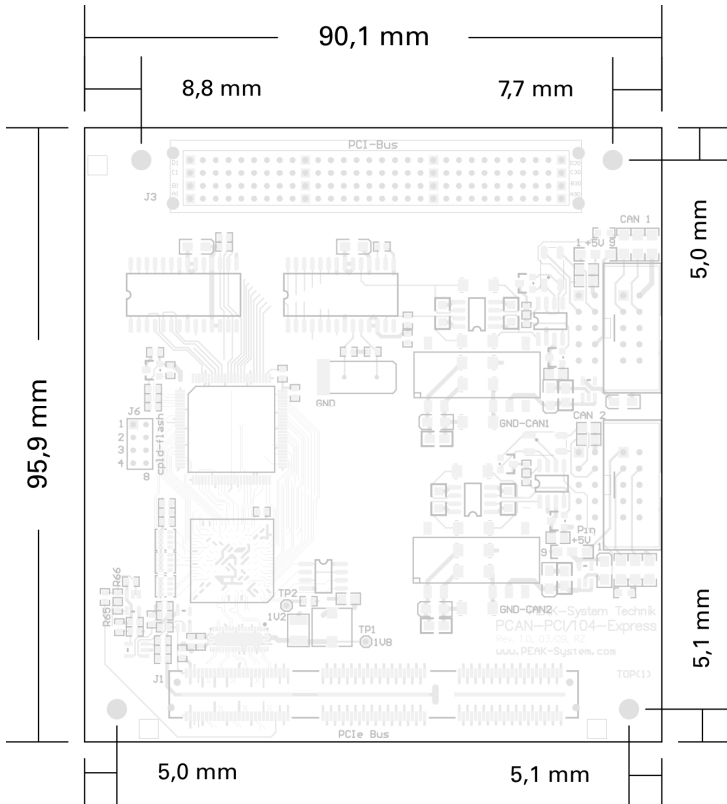


Figure 12: Dimension drawing PCAN-PCI/104-Express

The figure doesn't show the actual size of the product.

## Appendix C Quick Reference

### Software/Hardware Installation under windows

Before installing the PCAN-PCI/104-Express card in a PC/104 stack, setup the corresponding software package from the supplied CD (with Administrator privileges). Afterwards insert the card into a PC/104 stack of the switched off computer. The card is recognized by Windows and the driver is initialized. After the installation process is finished successfully you can find the entry "PCAN-PCI" in the branch "CAN-Hardware" of the Windows Device Manager.

### Getting Started under windows

Run the CAN monitor PCAN-View from the Windows Start menu as a sample application for accessing the PCAN-PCI/104-Express card. For initialization of the card select the desired CAN channel and the CAN bit rate.

### High-speed CAN connector (D-Sub, 9 pins)

